

09(3) : Thomas Rotation at the Newtonian Velocity V_N .

This procedure results in the Thomas precession:

$$\Delta \phi_T = 2\pi(\gamma - 1) = 2\pi\beta \quad - (1)$$

also

$$\gamma = \left(1 - \frac{v^2}{c^2}\right)^{-1/2} = \frac{dt}{d\tau} \quad - (2)$$

The Lorentz factor and where v is the Newtonian velocity.
 • relativistic kinetic energy is given immediately from eq. 1) as

$$T = (\gamma - 1)mc^2 = \beta mc^2 \quad - (3)$$

• the total energy as:

$$E = T + mc^2 = \gamma mc^2 = (1 + \beta)mc^2 \quad - (4)$$

• Lorentz factor γ can therefore be derived from the Thomas factor β , and from a Thomas rotation. All the fundamental quantities of EEC2 covariant physics can be derived from a Thomas rotation.

The usual way of deriving the Lorentz factor is to consider the invariance under Lorentz rotation:

$$x^\mu x_\mu = x'^\mu x'_\mu \quad - (5)$$

$$x^\mu = (ct, x, y, z) \quad - (6)$$

$$x'^\mu = (ct', x', y', z') \quad - (7)$$

$$c^2 t^2 - (x^2 + y^2 + z^2) = c^2 t'^2 - (x'^2 + y'^2 + z'^2) \quad - (8)$$

Applying eq. (8) to infinitesimals:

$$c^2 dt^2 - dr^2 = c^2 dt'^2 - dr'^2 \quad - (9)$$

$$dr^2 = dx^2 + dy^2 + dz^2 \quad - (10)$$

$$dr'^2 = dx'^2 + dy'^2 + dz'^2 \quad - (11)$$

The moving frame (ct', x', y', z') is the frame in which a particle is at rest, so its velocity in the S frame is zero and

$$dx'' + dy'' + dz'' = v'' dt'' = 0 \quad (12)$$

and

$$dx^2 + dy^2 + dz^2 = v^2 dt^2 \quad (13)$$

Eq. (9) becomes:

$$(c^2 - v^2) dt^2 = c^2 dt'^2 := c^2 d\tau^2 \quad (14)$$

where $d\tau$ is the interval of proper time, the time in the moving frame.

From Eq. (14) the Lorentz factor is:

$$\gamma = \left(1 - \frac{v^2}{c^2}\right)^{-1/2} = \frac{dt}{d\tau} \quad (15)$$

and is therefore derived from the Lorentz transformation of x . In plane polar coordinates the result of the Lorentz transformation

$$ds^2 = c^2 d\tau^2 = c^2 dt^2 - dx^2 - r^2 d\phi^2 \quad (16)$$

the relativistic kinetic energy is calculated from the work done:

$$W_{12} = \int_1^2 \underline{F} \cdot d\underline{r} = T_2 - T_1 \quad (17)$$

where the relativistic force is:

$$\underline{F} = \frac{d}{dt} (\gamma m \underline{v}) \quad (18)$$

$$\text{So: } T = W = \int \frac{d}{dt} (\gamma m \underline{v}) \cdot \underline{v} dt \quad (19)$$

in which

$$d\underline{r} = \underline{v} dt \quad (20)$$

It follows that:

$$\begin{aligned}
 T &= m \int_0^v v d(\gamma v) - (21) \\
 &= \gamma m v^2 - m \int_0^v \gamma v dv \\
 &= \gamma m v^2 + m c^2 (1 - v^2/c^2)^{1/2} - m c^2 \\
 &= (\gamma - 1) m c^2.
 \end{aligned}$$

So: $T = W = \int \underline{F} \cdot \underline{v} dt = (\gamma - 1) m c^2 = \beta m c^2 - (22)$

hence $\beta = \frac{\Delta \phi}{2\pi} - (23)$

The total energy is given by,

$$\begin{aligned}
 E &= T + m c^2 \\
 &= \gamma m c^2 = (1 + \beta) m c^2 - (24)
 \end{aligned}$$

The two methods of deriving the relativistic kinetic energy are similar, because both depend on rotations, but the conventional method requires additional concepts, notably the work done. For eq. (22), the Lorentz rotation produces the same work:

$$\beta = \frac{1}{m c^2} \int \underline{F} \cdot \underline{v} dt = \gamma - 1 - (25)$$

The four rotation (5) to (7) in plane polar coordinates is:

$$c^2 dt^2 - dr^2 - r^2 d\phi^2 = c^2 dt'^2 - dr'^2 - r'^2 d\phi'^2 - (26)$$

In the moving frame: $dr' + r' d\phi' = 0 - (27)$

so $c^2 dt^2 - dr^2 - r^2 d\phi^2 = c^2 dt'^2 = c^2 d\tau^2 - (28)$

with

$$v^2 dt^2 = dr^2 + r^2 d\phi^2 - (29)$$

so

$$(c^2 - v^2) dt^2 = c^2 d\tau^2 - (30)$$

this is equivalent to a Lorentz boost.

The infinitesimal line element in plane polar coordinates is derived from:

$$ds^2 = \underline{dr} \cdot \underline{dr} - (31)$$

also

$$\underline{r} = X \underline{i} + Y \underline{j} - (32)$$

"Vector Analysis Problem Solver", p. 1031). So:

$$\underline{r} = \underline{i} r \cos \phi + \underline{j} r \sin \phi - (33)$$

and

$$\underline{dr} = \frac{\partial \underline{r}}{\partial r} dr + \frac{\partial \underline{r}}{\partial \phi} d\phi - (34)$$

where

$$\frac{\partial \underline{r}}{\partial r} = \underline{i} \cos \phi + \underline{j} \sin \phi - (35)$$

and

$$\frac{\partial \underline{r}}{\partial \phi} = -\underline{i} r \sin \phi + \underline{j} r \cos \phi - (36)$$

so

$$ds^2 = dr^2 + r^2 d\phi^2 - (37)$$

and

$$\underline{dr} = (\cos \phi dr - r \sin \phi d\phi) \underline{i} - (38) \\ + (\sin \phi dr + r \cos \phi d\phi) \underline{j}$$

The derivation of eq. (37) starts from eq. (32). The cross notation produces:

$$\underline{r}' = X' \underline{i} + Y' \underline{j} - (39) \\ = r \cos(\phi + \omega t) \underline{i} + r \sin(\phi + \omega t) \underline{j}$$

3) S. & Thomas rotation is a four rotation defined by:

$$x^\mu = (ct, X, Y) = (ct, r \cos \phi, r \sin \phi) \quad (40)$$

and

$$x^{\mu'} = (ct, X', Y') = (ct, r \cos(\phi + \omega t), r \sin(\phi + \omega t)) \quad (41)$$

and

$$x^\mu x_\mu = x^{\mu'} x_{\mu'} \quad (42)$$

i.e.

$$c^2 t^2 - (X^2 + Y^2) = c^2 t'^2 - (X'^2 + Y'^2) \quad (43)$$

Eq. (43) means:

$$X'^2 + Y'^2 = X^2 + Y^2 = r^2 \quad (44)$$

because:

$$\cos^2 \phi + \sin^2 \phi = \cos^2(\phi + \omega t) + \sin^2(\phi + \omega t) = 1 \quad (45)$$

Therefore the Thomas rotation is a typical four rotation. It changes the infinitesimal element to

$$ds^2 = c^2 d\tau^2 = c^2 dt^2 - dr^2 - r^2 (d\phi + \omega dt)^2 \quad (46)$$

which the Thomas velocity is:

$$v = \omega r \quad (47)$$

As in No. 405(5), eq. (46) can be written as: (47)

$$ds^2 = \left(1 - \frac{v^2}{c^2}\right) (c^2 dt^2 - 2r^2 \Omega d\phi dt) - (dr^2 + r^2 d\phi^2)$$

where

$$\Omega = \omega \left(1 - \frac{v^2}{c^2}\right)^{-1} \quad (48)$$

It follows that the infinitesimal of time is changed

by Thomas rotation to:

$$dt' = \left(1 - \frac{v^2}{c^2}\right)^{1/2} dt. \quad (49)$$

The Thomas precession is defined by:

$$\begin{aligned}\Delta\phi &= \Omega dt' - \omega dt \quad (50) \\ &= 2\pi(\gamma - 1) \\ &= 2\pi\beta\end{aligned}$$

R.E.D., and the relativistic kinetic energy is:

$$T = mc^2\beta \quad (51)$$

The four rotations (8) and (43) both produce the relativistic kinetic energy (51). The Lorentz boost described by Eq. (8) is equivalent to the Thomas rotation (43), so the latter is the most fundamental concept of relativity.
