

1) Notes 58(7): Tetrad Method in the Calculation of Light Deflection without Torsion, and with Torsion.

The Schwarzschild metric (SM) is :

$$ds^2 = - \left(1 - \frac{2GM}{c^2 r}\right) c^2 dt^2 + \left(1 - \frac{2GM}{c^2 r}\right)^{-1} dr^2 + r^2 d\phi^2 + r^2 \sin^2 \phi d\theta^2 \quad \text{--- (1)}$$

The coordinate system being used is sketched in Fig (1).

Eq (1) is written in the curved S.I. units.

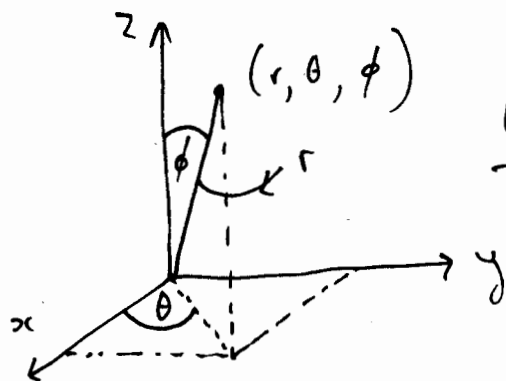


Fig (1)

Light travels along null paths,  
 $ds^2 = 0.$  --- (2)

Restrict consideration to a single plane through the centre of mass :

$$\theta = 0. \quad \text{--- (3)}$$

It follows that :

$$c^2 dt^2 = \left(1 - \frac{2GM}{c^2 r}\right)^{-2} dr^2 + r^2 \left(1 - \frac{2GM}{c^2 r}\right)^{-1} d\phi^2 \quad \text{--- (4)}$$

In the Minkowski metric :

$$\left(1 - \frac{2GM}{c^2 r}\right)^{-1} \rightarrow 1 \quad \text{--- (5)}$$

2) The metric corresponding to eq. (4) is:

$$g_{\mu\nu} = \begin{bmatrix} \left(1 - \frac{2GM}{c^2 r}\right)^{-2} & 0 \\ 0 & r^2 \left(1 - \frac{2GM}{c^2 r}\right)^{-1} \end{bmatrix} \quad - (6)$$

while the Minkowski metric is:

$$\eta_{ab} = \begin{bmatrix} 1 & 0 \\ 0 & r^2 \end{bmatrix} \quad - (7)$$

So we get:

$$g_{\mu\nu} = e_{\mu}^a e_{\nu}^b \eta_{ab} \quad - (8)$$

We extract the two tetrad elements:

$$e_{rr} = \left(1 - \frac{2GM}{c^2 r}\right)^{-1} \quad - (9)$$

$$e_{\phi\phi} = \left(1 - \frac{2GM}{c^2 r}\right)^{-1/2} \quad - (10)$$

If

$$2GM \ll c^2 r \quad - (11)$$

$$e_{rr} \rightarrow 1 + \frac{2GM}{c^2 r} + \dots \quad - (12)$$

$$e_{\phi\phi} \rightarrow 1 + \frac{GM}{r} + \dots \quad - (13)$$

3) The element  $g_{rr}$  means that  $r$  is not a straight line, it is the curve:

$$x(r) = x^{(0)} g_{rr} \quad \text{--- (14)}$$

where  $x^{(0)}$  is a proportionality. So  $x(r)$  is an orbit

It is found that:

$$c^2 \frac{dg_{rr}}{dr} = - \frac{2GM}{r^2} \quad \text{--- (15)}$$

The Newtonian force between a photon of mass  $m$  and the sun of mass  $M$  is:

$$F = - \frac{GmM}{r^2} \quad \text{--- (16)}$$

The force from eq. (15) is:

$$F = - mc^2 \frac{dg_{rr}}{dr} = - \frac{2GmM}{r^2} \quad \text{--- (17)}$$

This is twice the Newtonian force (16), and is the photon rest energy:

$$E_0 = mc^2 = h\nu \quad \text{--- (18)}$$

multiplied by  $dg_{rr}/dr$ . Eq. (18) is the Planck / Einstein / de Broglie equation. So the

Newtonian inverse square law is only half the

answer, as found experimentally.

4) The force (17) is:

$$F = mg = -mc^2 \frac{dq_{rr}}{dr} \quad - (19)$$

The acceleration due to gravity is:

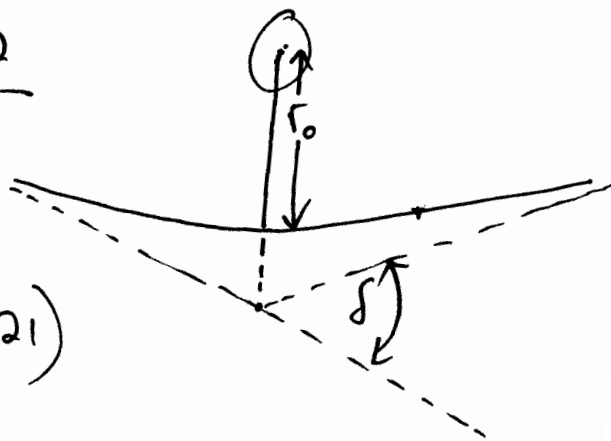
$$g = -c^2 \frac{dq_{rr}}{dr} \quad - (20)$$

using the equivalence of gravitational and inertial mass.

The angle of deflection is twice that expected from the Newtonian orbit:

$$\delta(\text{Newton}) = \frac{2MG}{c^2 r_0} \quad - (21)$$

Fig 2



where  $r_0$  is the distance of closest approach. So:

$$\delta(\text{Schwarzschild}) = \frac{4MG}{c^2 r_0} \quad - (22)$$

The calculation has been carried out in the correct S.I. units. So this is our Schwarzschild,  $T = 0$  case.

## 5) The Effect of Cartan Torsion

The Sasakian geometry is:

$$R \wedge \eta = 0, T = 0 \quad - (23)$$

which is the Einstein-Hilbert geometry, in which the Riemann tensor is antisymmetric in its first two indices and also its last two indices. In the presence of torsion:

$$R \wedge \eta = d \wedge T + \omega \wedge T \neq 0 \quad - (24)$$

so the Riemann tensor is no longer antisymmetric in its first two indices. This means that the Einstein-Hilbert equation is no longer true. However, the second Bianchi identity of Cartan geometry is still true:

$$D \wedge R := 0. \quad - (25)$$

In the EH geometry:

$$T = d \wedge \eta + \omega \wedge \eta = 0 \quad - (26)$$

so:

$$d \wedge \eta = -\omega \wedge \eta. \quad - (27)$$

In the presence of torsion:

$$\boxed{d \wedge \eta = -\omega \wedge \eta + T} \quad - (28)$$

So the mathematical task is to find the elements of the spi connection from eqs. (12), (13) and (26) for perturb with a small  $\delta T$ :

$$d\Lambda q \rightarrow -\omega \Lambda q + \delta T \quad (29)$$

In the first approximation the spi connection can be assumed to be changed only slightly, so:

$$d\Lambda q \rightarrow -\omega_0 \Lambda q + \delta T \quad (30)$$

where  $\omega_0$  is the baseline spi connection from eq. (26). We may proceed very roughly by inserting a  $\delta T$  by inspection. It is clear that the tetrad element (12) will be changed by  $\delta T$ . The role of deflection (20) and the acceleration  $g$  will also change.

The complete problem is defined by the structure equations and Bianchi identities of certain geometry:

$$T = D\Lambda q \quad (31)$$

$$R = D\Lambda \omega \quad (32)$$

$$D\Lambda T = R\Lambda q \quad (33)$$

$$D\Lambda R = 0 \quad (34)$$

