

11(3) : The Torsion based Field Equation

Ernst derived his field equation from the equation

$$D \wedge R = k D \wedge N = 0 \quad - (1)$$

in the tensor form:

$$D^\mu G_{\nu\mu} = k D^\mu T_{\nu\mu} \quad - (2)$$

From paper 88 it is now known that eq. (1) is a special case of

$$D \wedge T := R \wedge \eta \quad - (3)$$

In this special case:

$$R \wedge \eta = 0 \quad - (4)$$

which can be written as:

$$R^a{}_{\sigma\mu\nu} + R^a{}_{\nu\sigma\mu} + R^a{}_{\mu\nu\sigma} = 0 \quad - (5)$$

Introducing the S-torsion this can be written as:

$$D_\sigma S^a{}_{\mu\nu} + D_\nu S^a{}_{\sigma\mu} + D_\mu S^a{}_{\nu\sigma} = 0 \quad - (6)$$

This equation can be written as:

$$\boxed{D_\mu \tilde{S}^{a\mu\nu} = 0}, \quad - (7)$$

where

$$\tilde{S}^{a\mu\nu} = -\tilde{S}^{a\nu\mu} \quad - (8)$$

We now introduce the two-form:

$$2) \quad \tilde{N}^{\alpha\mu\nu} = -\tilde{N}^{\alpha\nu\mu} \quad - (9)$$

From paper 88 this Noether form is defined by:

$$D \wedge N^a := N^a_b \wedge q^b \quad - (10)$$

and has the units of mass per unit area. In the special case we are considering:

$$D \wedge N^a = 0 \quad - (11)$$

i.e.

$$D_\sigma N^a_{\mu\nu} + D_\nu N^a_{\sigma\mu} + D_\mu N^a_{\nu\sigma} = 0 \quad - (12)$$

which is

$$D_\mu \tilde{N}^{\alpha\mu\nu} = 0 \quad - (13)$$

So combining eqs. (7) and (13)

$$\boxed{D_\mu \tilde{S}^{\alpha\mu\nu} = k D_\mu \tilde{N}^{\alpha\mu\nu} = 0} \quad - (14)$$

where:

$$k = \frac{8\pi G}{c^2} = 1.86595 \times 10^{-26} \text{ m kg m}^{-1} \quad - (15)$$

is Einstein's constant where G is Newton's constant. A possible solution of eq. (14) is

$$\boxed{\tilde{S}^{\alpha\mu\nu} = k \tilde{N}^{\alpha\mu\nu}} \quad - (16)$$

3) Units Check

$$\tilde{S} = m^{-1}, k = m / \text{kgm}, N = \text{kgm} a^{-2} \checkmark \checkmark$$

Eq. (14) can be written as:

$$\begin{aligned} D_\sigma S_{\mu\nu}^a + D_\nu S_{\sigma\mu}^a + D_\mu S_{\nu\sigma}^a & - (17) \\ & = k (D_\sigma N_{\mu\nu}^a + D_\nu N_{\sigma\mu}^a + D_\mu N_{\nu\sigma}^a) \\ & = 0 \end{aligned}$$

i.e.:

$$D \wedge S^a = k D \wedge N^a = 0 \quad - (18)$$

in differential form notation. Written out in full, eq. (18) is:

$$\begin{aligned} d \wedge S^a + \omega^a_b \wedge S^b & = k (d \wedge N^a + \omega^a_b \wedge N^b) \\ & = 0, \quad - (19) \end{aligned}$$

a particular solution of which is:

$$S_{\mu\nu}^a = k N_{\mu\nu}^a \quad - (20)$$

However there are more general solutions of eq. (19) than that of eq. (20).

4) The particular solution (20) means that if there is no mass anywhere in the universe:

$$N^a_{;\mu\nu} = 0 \quad - (21)$$

which means that there is no curvature:

$$R^a_{\mu\nu\sigma} = D_\mu S^a_{\nu\sigma} = 0. \quad - (22)$$

The more general equation (18) means that it is possible to write:

$$D \wedge S^a = 0 \quad - (23)$$

$$D \wedge N^a = 0 \quad - (24)$$

Eq. (23) is the Bianchi equation and eq. (24)

is the conservation of energy. In order to relate physics to geometry it is necessary to write:

$$D \wedge S^a = k(D \wedge N^a) = 0 \quad - (25)$$

Eqs. (20) and (25) offer two different tensor based cosmologies. The first step towards a development is to deduce the Newtonian limit. This will be done in the next note.