

1) 94(4): Time Dependent Resource Structures from the  
Ampere Maxwell Law.

In general this law is ECE theory is:

$$\underline{\nabla} \times \underline{B} = \frac{1}{c^2} \frac{\partial \underline{E}}{\partial t} + \mu_0 \underline{J} \quad - (1)$$

where:  $\underline{E} = -\underline{\nabla} \phi - \frac{\partial \underline{A}}{\partial t} - c\omega^2 \underline{A} + c\phi \underline{\omega}$  - (2)

If we consider the law (1) to be:

$$\frac{\partial \underline{E}}{\partial t} = c^2 (\underline{\nabla} \times \underline{B} - \mu_0 \underline{J}) \quad - (3)$$

$$= -\underline{\nabla} \frac{\partial \phi}{\partial t} - \frac{\partial^2 \underline{A}}{\partial t^2} - \frac{\partial}{\partial t} (c\omega^2 \underline{A}) + \frac{\partial}{\partial t} (c\phi \underline{\omega})$$

For the most general resource equation of time-dependent type is:

$$\frac{\partial^2 \underline{A}}{\partial t^2} + c \left( \frac{\partial \omega^2}{\partial t} \right) \underline{A} + c\omega^2 \frac{\partial \underline{A}}{\partial t} = c \left( \frac{\partial \phi}{\partial t} \right) \underline{\omega} + c\phi \left( \frac{\partial \underline{\omega}}{\partial t} \right) + c^2 \mu_0 \underline{J} - \underline{\nabla} \frac{\partial \phi}{\partial t} - c^2 \underline{\nabla} \times \underline{B} \quad - (4)$$

If there is no current density and no charge density this reduces to:

2)

$$\frac{\partial^2 \underline{A}}{\partial t^2} + \omega^2 \frac{\partial \underline{A}}{\partial t} + c \left( \frac{\partial \omega^2}{\partial t} \right) \underline{A} = -c^2 \underline{\nabla} \times \underline{B} \quad - (5)$$

There is resonance in  $\underline{A}$  if and only if:

- 1) The scalar part,  $\omega^2$ , of  $\underline{E}$  spin convention is non-zero.
- 2) The time derivative  $\partial \omega^2 / \partial t$  is non-zero.
- 3)  $\underline{\nabla} \times \underline{B}$  is non-zero and also time dependent.

When investigating various claims, resonance structures such as this must be systematically developed, so of time dependent and space dependent, and the conditions needed for resonance identified. An example consists of conditions 1) to 3)

above. These conditions show already that the magnetic field in the design must be both space and time dependent

3) In addition to eqn. (1) there exists the  
Coulomb law:

$$\underline{\nabla} \cdot \underline{E} = \rho / \epsilon_0 \quad - (6)$$

i.e.:

$$\underline{\nabla} \cdot \left( c \underline{\phi} \underline{\omega} - \underline{\nabla} \phi - \frac{\partial \underline{A}}{\partial t} - c \underline{\omega} \cdot \underline{A} \right) = \frac{\rho}{\epsilon_0} \quad - (7)$$

In the absence of charge:

$$\underline{\nabla} \cdot \left( \frac{\partial \underline{A}}{\partial t} + c \underline{\omega} \cdot \underline{A} \right) = 0 \quad - (8)$$

So  $\underline{\omega} \cdot$  may be eliminated between eqns.

(5) and (8). Eqn. (8) is:

$$\underline{\nabla} \cdot \frac{\partial \underline{A}}{\partial t} = -c \underline{\nabla} \cdot (\underline{\omega} \cdot \underline{A}) \quad - (9)$$

$$\underline{\nabla} \cdot \frac{\partial \underline{A}}{\partial t} = -c \left( \underline{A} \cdot \underline{\nabla} \underline{\omega} + \underline{\omega} \cdot \underline{\nabla} \cdot \underline{A} \right) \quad - (10)$$

Therefore  $\underline{\omega} \cdot$  is governed by eqns. (5) and (10).

These two equations must be solved simultaneously.

From eqn. (10):

$$\underline{\nabla} \cdot \left( \frac{\partial \underline{A}}{\partial t} + c \underline{\omega} \cdot \underline{A} \right) = -c \underline{A} \cdot \underline{\nabla} \underline{\omega} \quad - (11)$$

4) The integration of eq. (11) must now be carried out. For this we use the divergence theorem.

For any well behaved vector field  $\underline{V}(\underline{r})$  defined within a volume surrounded by a closed surface  $S$ :

$$\oint_S \underline{V} \cdot \underline{n} da = \int_V \underline{\nabla} \cdot \underline{V} d^3r \quad - (12)$$

Thus for Gauss law:

$$\int_V (\underline{\nabla} \cdot \underline{E} - \frac{\rho}{\epsilon_0}) d^3r = 0 \quad - (13)$$

i.e. 
$$\oint_S \underline{E} \cdot \underline{n} da = \frac{1}{\epsilon_0} \int_V \rho(\underline{r}) d^3r \quad - (14)$$

So the integration of eq. (11) is - (15)

$$\oint_S \left( \frac{\partial \underline{A}}{\partial t} + c \omega^2 \underline{A} \right) \cdot \underline{n} da = -c \int_V \underline{A} \cdot \underline{\nabla} \omega^2 d^3r$$

i.e.:

$$\oint_S \frac{\partial \underline{A}}{\partial t} \cdot \underline{n} da = - \oint_S c \omega^2 \underline{A} \cdot \underline{n} da - c \int_V \underline{A} \cdot \underline{\nabla} \omega^2 d^3r \quad - (16)$$

Eqn. (16) is :

5)

$$\oint_S \frac{\partial \underline{A}}{\partial t} \cdot \underline{n} \, da = -c \oint_S \underline{A} \cdot \underline{n} \, da - c \int_V \underline{A} \cdot \underline{\nabla} \omega_c \, d^3r \quad (17)$$

and is a relation between  $\omega_c$  and  $\underline{A}$ .

Furthermore it expresses  $\frac{\partial \underline{A}}{\partial t}$  in terms of  $\underline{A}$ .

- Therefore the correct way to solve eq. (5) is simultaneously with eq. (15).

If possible this should be done by computer for the various modes of  $\underline{\nabla} \times \underline{B}$ .  
It can be seen that  $\omega_c$  is eliminated and that eq. (5) reduces to an undamped oscillator because  $\partial \underline{A} / \partial t$  is eliminated in favour of  $\underline{A}$ .

Conclusion.

For various modes of  $\underline{\nabla} \times \underline{B}$ ,  $\underline{A}$  can go to infinity. There is no need to model  $\omega_c$ , because it can be expressed in terms of  $\underline{A}$ .